

On a General Class of Solutions of a Nonholonomic Extension of Optical Pulse Equation

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Abstract: A Nonholonomic extension of an equation obeyed by short pulse in non-linear optics is obtained. A general class of solutions of such an equation is obtained with the help of Riemann-Hilbert technique.

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1. Introduction

Recent literature of integrable systems has been enriched by quite a few publications discussing a new class of systems which are nonholonomic in the sense that they are accompanied by differential constraints [1] those cannot be explicitly solved. This actually enlarges the integrable class itself. People have studied some interesting cases associated with AKNS [2] systems Kaup-Newell equation and so on. Here in this communication we have obtained a nonholonomic generalization of a very special type of equation which governs the propagation of a short optical pulse in nonlinear optics [3]. In the second part we have shown how a general class of solutions of such an equation can be generated through the Riemann Hilbert method [6].

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2. Formulation

To start with, we consider the Lax pair

$$\psi_x = L\psi \quad (1)$$

$$\psi_t = M\psi \quad (2)$$

$$L = \begin{pmatrix} -\phi_x & 1 \\ -\lambda & \phi_x \end{pmatrix}; N = \begin{pmatrix} A & B \\ C & -A \end{pmatrix}$$

whence consistency leads to

$$\phi_{xt} + A_x - C - \lambda B = 0 \quad (3)$$

$$B_x + 2A + 2\phi_x B = 0 \quad (4)$$

$$C_x + 2\lambda A - 2\phi_x C = 0 \quad (5)$$

Next we set

$$A = a_{-1}\lambda^{-1} + a_2 + a_1\lambda + a_0\lambda^2 \quad (6)$$

$$B = b_{-1}\lambda^{-1} + b_2 + b_1\lambda + b_0\lambda^2 \quad (7)$$

$$C = c_{-1}\lambda^{-1} + c_2 + c_1\lambda + c_0\lambda^2 \quad (8)$$

The unknown coefficients are determined in a recursive manner and are given as

$$\begin{aligned} a_0 &= b_0 = 0 \\ c_0 &= \eta_2 \\ a_1 &= \eta_2 \phi_x \\ b_1 &= -\eta_2 \end{aligned} \quad (9)$$

$$\begin{aligned} c_1 &= \frac{1}{2}\eta_2 (\phi_{xx} + \phi_x^2) \\ a_2 &= -\frac{1}{4}\eta_2 (\phi_{xxx} - 2\phi_x^3) \\ b_2 &= \frac{1}{2}\eta_2 (\phi_{xx} - \phi_x^2) \\ c_{-1} &= \eta_1 \exp(2\phi) \end{aligned} \quad (10)$$

where η_1 and η_2 are constants .

Along with ;

$$a_{-1x} = \eta_1 \exp(2\phi) \quad (11)$$

$$b_{-1xx} + 2\phi_{xx}b_{-1} + 2\phi_x b_{-1x} + 2\eta_1 \exp(2\phi) = 0 \quad (12)$$

$$c_{2xx} - 2\phi_{xx}c_2 - 2\phi_x c_{2x} + 2\eta_1 \exp(2\phi) = 0 \quad (13)$$

and the nonlinear equation ;

$$\phi_{xt} + a_{2x} - c_2 - b_{-1} = 0 \quad (14)$$

It is interesting to note that c_2 , b_{-1} are to be determined only as solutions of eq(8) and eq(9), which really leads to nonlocal nonholonomic constraints. To proceed further we consider the special case $\eta_1 = 0$, which leads to $a_{-1} = \text{constant}$; along with $c_2 = \eta_3 \exp(2\phi)$ and $b_{-1} = \eta_4 \exp(-2\phi)$ so that the nonlinear equations turn out to be;

$$\phi_{xt} = \phi_{xxxx} - 6\phi_x^2 \phi_{xx} + 2\eta \sinh(2\phi). \quad (15)$$

by proper choice of η_i . Equation (11) is nothing but the nonlinear equation obeyed by a short optical pulse propagating in an optical fibre. So, if we assume $\eta_1 \neq 0$, then eq(10) can be considered as a nonholonomic generalization of eq (11)⁵.

3. General Solutions

To analyze the solutions of the new equation [14] we take recourse to the Riemann-Hilbert technique [4]. The usual approach is to assume that the analytic wave function $\phi(\lambda)$, with the constraint

$$\phi_1(\lambda) \phi_2(\lambda) = G(\lambda) \quad (16)$$

where ϕ_1, ϕ_2 are the boundary values of ϕ on the interior and exterior of a close Jordan curve Γ in the complex λ plane. In case of Riemann - Hilbert problem with simple poles we assume $G(\lambda) = 1$. Let ϕ_0 be the starting seed solution of eq [14] with ψ_0 , the corresponding Lax eigenfunction [5]. We can set

$$\psi = \chi \psi_0 \quad (17)$$

If the Lax operator corresponding to ϕ_0 be denoted as L_0 , then one gets

$$L = \chi_x \chi^{-1} + \chi L_0 \chi^{-1} \quad (18)$$

To formulate the Riemann-Hilbert problem we assume that χ contains simple pole in λ - plane,

$$\chi = \left(1 + \frac{S}{\lambda - \lambda_1} \right) \quad (19)$$

along with

$$\chi^{-1} = \left(1 + \frac{R}{\lambda - \lambda_1} \right) \quad (20)$$

From the condition $\chi \chi^{-1} = 1$ one gets

$$S = -R = (\lambda_1 - \mu_1) P \quad (21)$$

where P is the projection operator ($P^2 = P$). Also from Eq.[18] we get

$$L = L_0 - (\lambda_1 - \mu_1)[P, \sigma_-] \quad (22)$$

The Lax operator has some interesting symmetry property

$$\sigma_1 L^T \sigma_1 = L(-\phi, \lambda) \quad (23)$$

$$\sigma_2 L^T \sigma_2 = -L(\phi, \lambda) \quad (24)$$

with σ_1 σ_2 being Pauli matrices and $\sigma_- = \sigma_1 - i\sigma_2$. An easy seed solution is $\phi = 0$, whence we require the Lax eigenfunction as solution of ;

$$\psi_x = \begin{pmatrix} 0 & 1 \\ -\lambda & 0 \end{pmatrix} \psi \quad (25)$$

$$\text{and } \psi_t = \begin{pmatrix} \eta_1 x \lambda^{-1} & -\eta_1 x^2 \lambda^{-1} - \eta_2 \lambda \\ \eta_1 \lambda^{-1} - \eta_1 x^2 + \eta_2 \lambda^2 & -\eta_1 x \lambda^{-1} \end{pmatrix} \psi \quad (26)$$

writing out in component form we get one partial differential equation

$$\psi_{2t} + (-\eta x^2 + \eta \lambda^{-1} - \lambda^2) \frac{\psi_{2x}}{\lambda} = -\eta x \lambda^{-1} \psi_2 \quad (27)$$

Now it is easy to show that an equation of the form ;

$$f(x)\omega_x + g(y)\omega_y = [\delta_1(x) + \delta_2(y)]\omega \quad (28)$$

has a solution of the form

$$\omega = \exp \left[\int \frac{\delta_1(x)}{f(x)} dx + \int \frac{\delta_2(y)}{g(y)} dy \right] \Theta \left(\int \frac{1}{f(x)} dx - \int \frac{1}{g(y)} dy \right) \quad (29)$$

where Θ is an arbitrary function of its argument. Finally using the explicit of function δ_1 and δ_2 from Eqs.[26], we arrive at

$$\psi_1 = \frac{\mu(\theta)}{\sqrt{\lambda - \eta \lambda^{-1} x^2}} \quad (30)$$

$$\psi_2 = \frac{\eta \lambda^{-1} x \mu(\theta)}{\sqrt{\lambda - \eta \lambda^{-1} x^2}} + \frac{\mu_x(\theta)}{\sqrt{\lambda - \eta \lambda^{-1} x^2}} \quad (31)$$

where $\theta = t + \frac{1}{2a\eta\lambda^{-1}} \ln \left(\frac{x+a}{x-a} \right)$, along with $a^2 = \frac{\lambda^3}{\eta}$. The Projection operator is now constructed as,

$$P = \frac{|p\rangle\langle q|}{\langle p|q\rangle} \quad (32)$$

where $|p\rangle$ and $|q\rangle$ are given by;

$$|p\rangle = \begin{pmatrix} a_1\psi_1(\lambda_1) \\ a_2\psi_2(\lambda_1) \end{pmatrix} = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} \quad (33)$$

$$|q\rangle = \begin{pmatrix} b_1\psi_1(\mu_1) \\ b_2\psi_2(\mu_1) \end{pmatrix} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \quad (34)$$

where Eq.(22) leads to

$$\phi_x = (\lambda_1 - \mu_1) \frac{u_1 v_2}{u_1 v_1 + u_2 v_2} \quad (35)$$

The form of the solution is clearly different from the usual soliton like profile sustained by original optical pulse equation . The absence of any wavefront $(x - vt)$ suggests that it is a nonpropagating solution .

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